

## What is Octo-tiger?

- ▶ Octo-tiger simulates self-gravitating astrophysical fluids. It is used in the modeling of interacting binary star systems
- ▶ To compute the gravitational field, it uses the fast multipole method
- ▶ Octo-tiger uses HPX to for parallelisation to run on distributed computing clusters

## What are the Performance Bottlenecks?

- ▶ Most time is spent calculating the gravitational field with the fast multipole method (FMM)
- ▶ Within the FMM methods, most time is spent computing the interactions of a cell with its close neighbors

## A Closer Look at the old Interaction Calculation

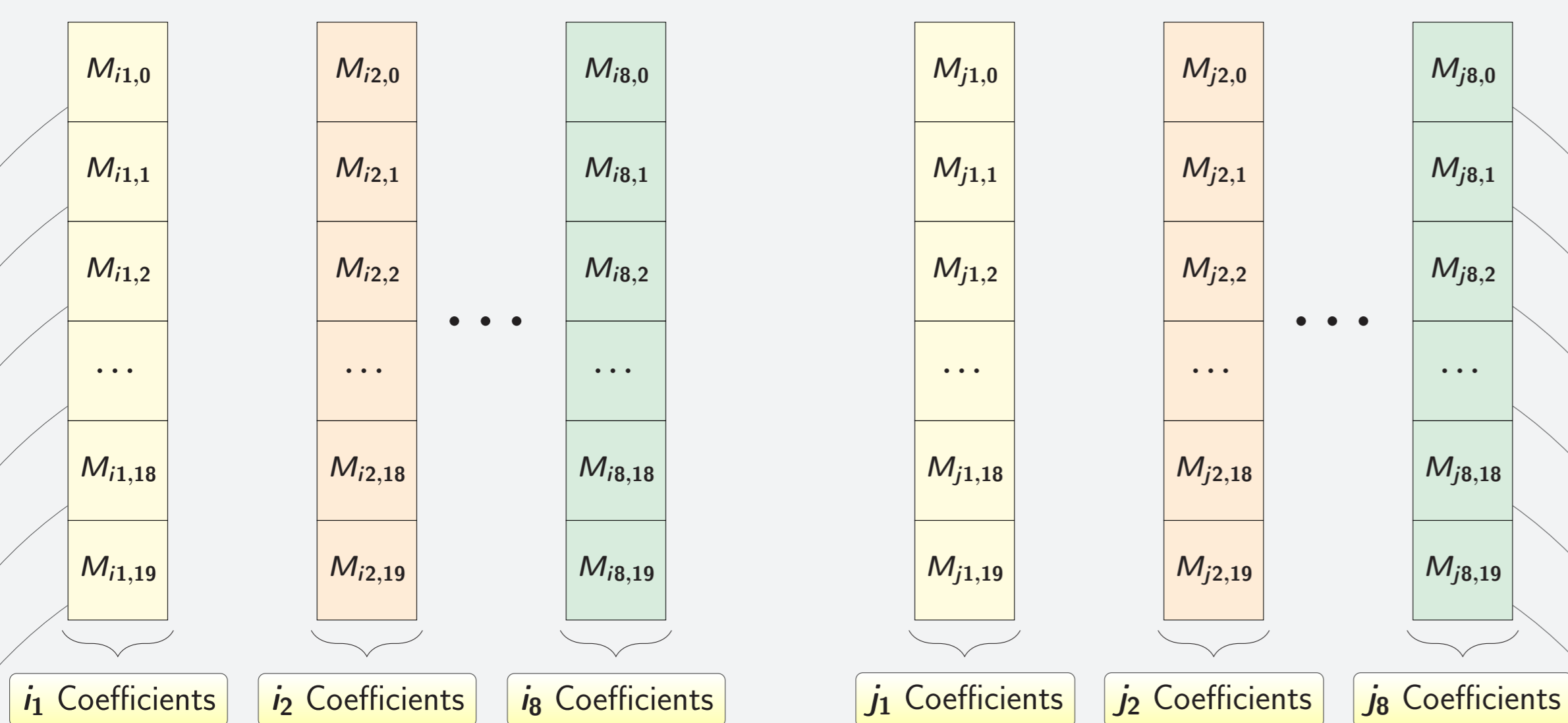
### 1. Find Interaction Pair $i,j$ (load 8 at once)

#### Interaction list

Cell index 1	...	...	...	$i1$	$i2$	...	$i8$	...	...	...
Cell index 2	...	...	...	$j1$	$j2$	...	$j8$	...	...	...

Load 8 interaction pairs to utilize vector units

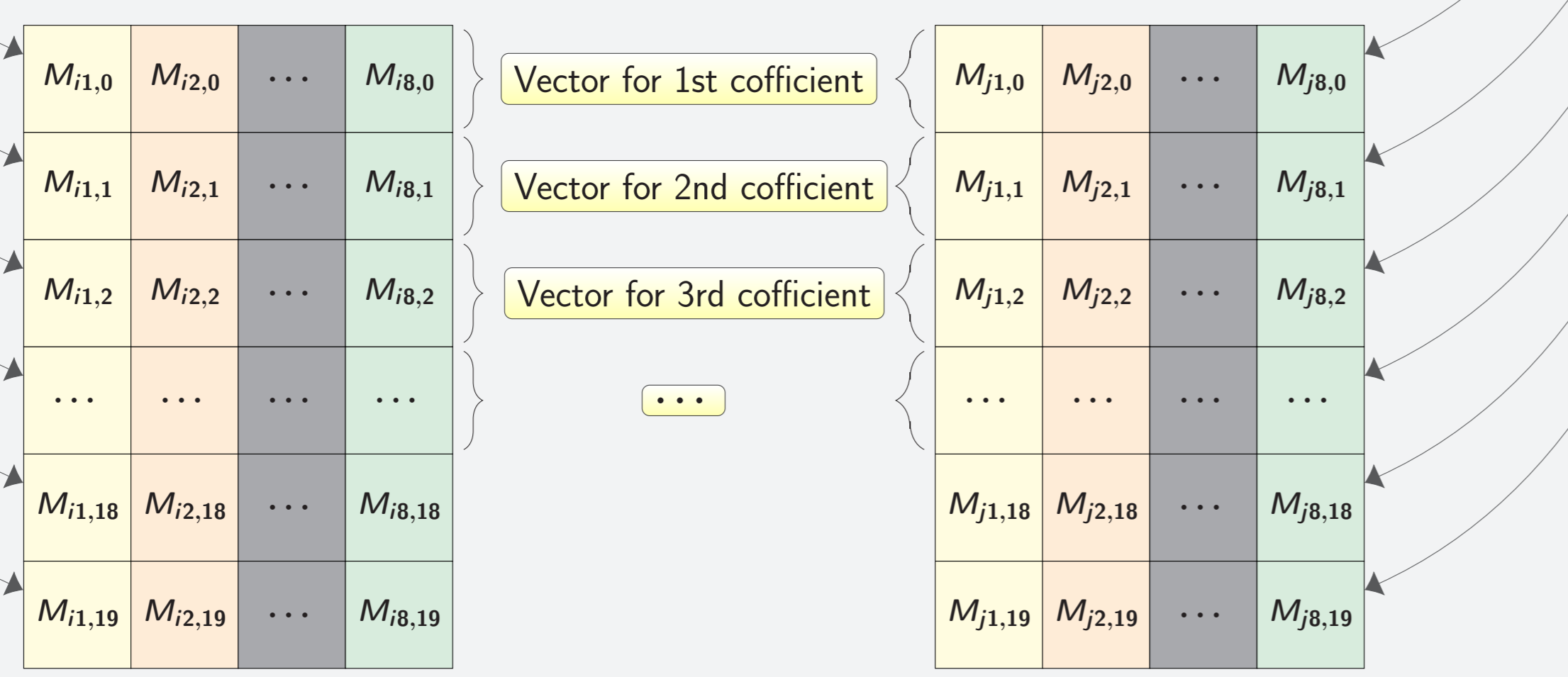
### 2. Load Coefficients of $i,j$ (Array of Structs)



Each column is consecutive in memory

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### 3. Data Alignment (into Vector Registers)



Vector elements of length 8 (AVX512)  
Each row needs to be consecutive in memory

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### 4. Calculate Interactions (and Store Results)

Do vectorized math:

$$L_q^{f,(0)} := \sum_l [M_{l,q}^{(0)} D^{(0)}(R_{l,q}) + M_{l,m}^{(1)} D_m^{(1)}(R_{l,q}) + \dots] + \dots$$

$$L_{q,m}^{f,(1)} := \sum_l \dots$$

Equation and required data depends on the interaction type (multipole-multipole, (monopole-monopole, mixed interactions))

$L_{i1,0}$	$L_{i2,0}$	...	$L_{i8,0}$
$L_{i1,1}$	$L_{i2,1}$	...	$L_{i8,1}$
...	...	...	...
$L_{i1,19}$	$L_{i2,19}$	...	$L_{i8,19}$

Vector results have to be scattered into Array of Structs (AoS) data-structure

## Insights

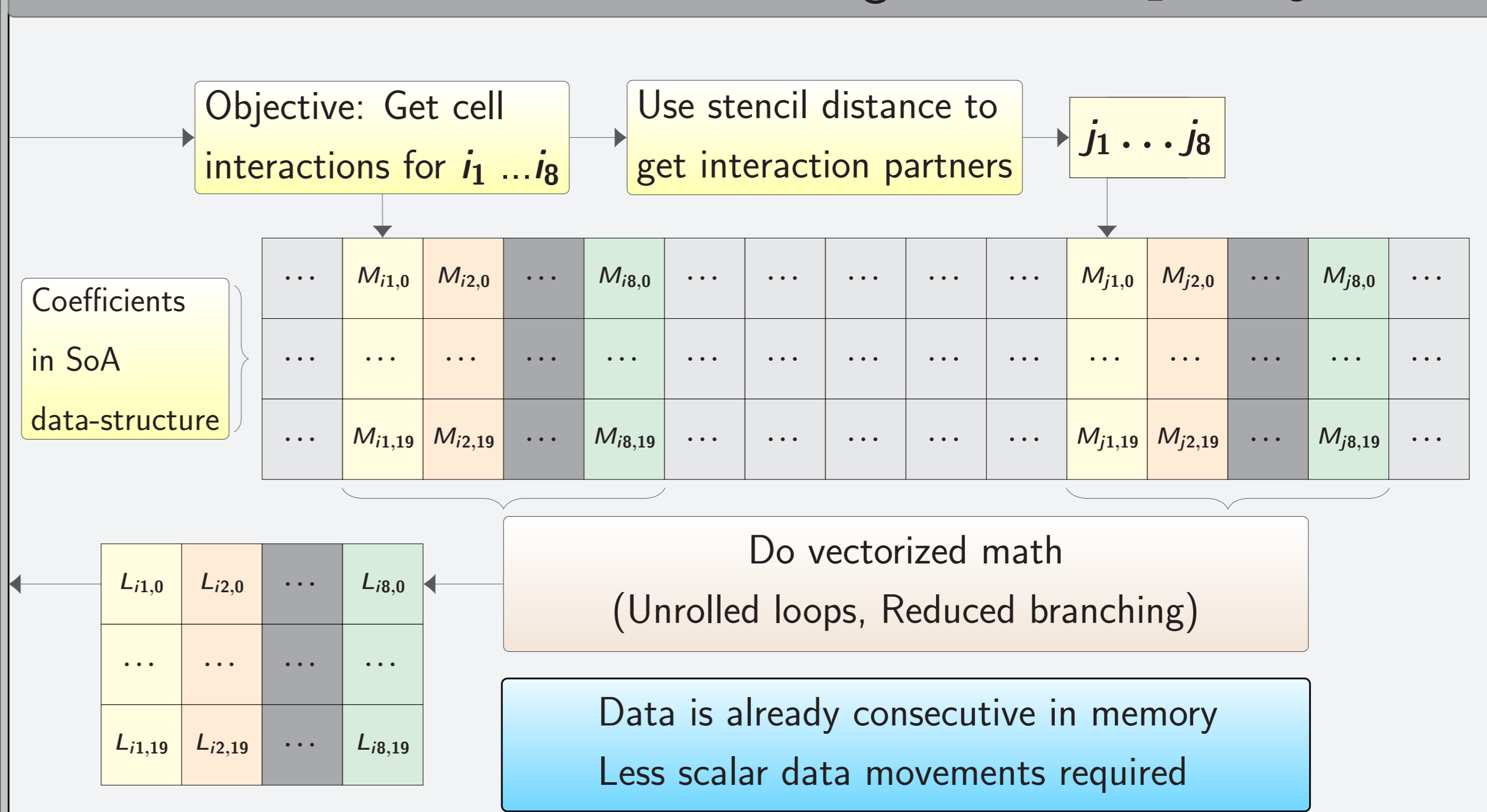
- ▶ The coefficient data of a cell is stored in a struct instance which is consecutive in memory. We cannot load a coefficient vector in one step
- ▶ Loading the coefficients of different cells into a vector register involves expensive gather operations
- ▶ We need to scatter the results from the vector register back into the structs

## How to Improve the Performance

- ▶ Store coefficient data and results component-wise as Struct of Array (SoA)
  - ▷ Coefficients can be loaded directly into the vector registers
  - ▷ Interaction partners need to be next to each other in the memory
  - ▷ Therefore, use stencil approach instead of interaction list

## New Interaction Method

### Calculate Interactions for given Cells $i_1 \dots i_8$



## Node-level Performance Comparison of both Interaction Methods

Platform (using one core only)	Old Version	New Version	Speedup
Intel Xeon Phi 7210 @ 1.30GHz	21706.20s	6855.76s	3.17
Intel Xeon E5-2630 v3 @ 2.40GHz	1964.89s	1367.79s	1.44
Intel Xeon E5-2660 v3 @ 2.60GHz	1910.04s	1365.59s	1.40

Octo-tiger arguments for used scenario:

-t1 -Disableoutput -Problem=moving\_star -Max\_level=6 -Odt=0.3 -Stoptime=0.2 -Xscale=20.0 -Omega=0.1 -Stopstep=20

## Conclusion

- ▶ By switching from an AoS data structure to an SoA one, we achieve a speedup of over 3.17 on KNL CPUs and a speedup of about 1.44 for Haswell CPUs.
- ▶ The new data structure is thus far only used for the calculations of the interactions. The speedup can be further improved by completely eliminating the old AoS data-structure and with that any conversions between the two structures

## Acknowledgments

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## References

- [1] Dominic C. Marcelllo, Kundan Kadam, Geoffrey C. Clayton, Juan Frank, Hartmut Kaiser, and Patrick M. Motl. Introducing octo-tiger/hpx: Simulating interacting binaries with adaptive mesh refinement and the fast multipole method. *Proceedings of Science*, under review.